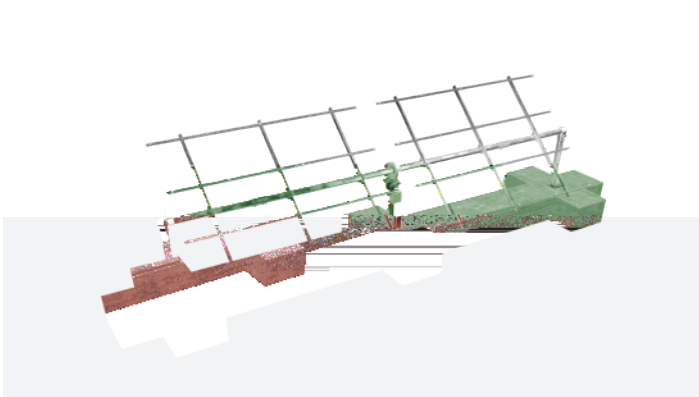


质量保证



EMC, 1999

GPS

	MRac		
GPS			
	KWP		
	$\pm$		
	< m/s	Q B	,AI -T ()
	+ $\pm$		
	mm+	IP	
	DC V		
